**Time** | **Date** | **Conference Welcome**
---|---|---
7:45 | 31 May Tuesday | Steven Waslander & Jonathan Kelley
7:50 | | Sponsored Talk
8:10 | | Keynote Speaker #1: Loudes Agapito, University College London
9:15 | | Coffee Break
9:30 | | Oral Session 1: 3D Vision
8:10 | | Keynote Speaker #2: Maurice Fallon, University of Oxford
9:15 | | Coffee Break
12:30 | | Poster session and industry booths
12:30 | | Lunch Break
13:45 | | Student Networking Event
14:45 | | Welcome Event (In-Person)

**Time** | **Date** | **Conference Welcome**
---|---|---
7:45 | 1 June Wednesday | Steven Waslander & Jonathan Kelley
7:50 | | Sponsored Talk
8:10 | | Keynote Speaker #2: Maurice Fallon, University of Oxford
9:15 | | Coffee Break
9:30 | | Oral Session 3: Learning-based Planning and Perception
12:30 | | Lunch Break
13:45 | | Student Networking Event
14:45 | | Welcome Event (In-Person)
<table>
<thead>
<tr>
<th>Time</th>
<th>Date</th>
<th>Event</th>
</tr>
</thead>
<tbody>
<tr>
<td>12:45</td>
<td>6/2/2022</td>
<td>CRV posters (listing poster board id and paper title)</td>
</tr>
<tr>
<td>16:45</td>
<td>6/2/2022</td>
<td>Awards Ceremony (joint CRV &amp; AI session) [Gather town]</td>
</tr>
</tbody>
</table>

**Poster session and industry booths**
Location: Gather town
Chair: Helge Rhodin & Hsiu-Chin Lin

Join Gather town in your browser and roam around using the arrow keys. Allow the app to access your camera and mic, to be able to chat with the other attendees as in a normal poster session. Open posters by moving closer and pressing ‘x’ on your keyboard.

**Hints**
1. You can hear and be heard by people roughly half a screen away. Enter a private space (e.g., table indicated by gray highlight) to speak in privacy.
2. You can go in stealth/ghost mode by pressing ‘g’
3. If running into trouble, disable your VPN, use a modern browser, and refresh the browser tab.

**CRV posters**
- 10  Understanding the impact of image and input resolution on deep digital pathology patch classifiers
- 26  Attention based Occlusion Removal for Hybrid Telepresence Systems
- 32  Improving tracking with a tracklet associator
- 37  Anomaly Detection with Adversarially Learned Perturbations of Latent Space
- 38  An Exact Fast Fourier Method for Morphological Dilation and Erosion Using the Umbra Technique
- 46  Monocular Robot Navigation with Self-Supervised Pretrained Vision Transformers
- 47  TemporalNet: Real-time 2D-3D Video Object Detection
- 48  Safe Landing Zones Detection for UAVs Using Deep Regression

**Awards Ceremony (joint CRV & AI session) [Gather town]**
Join Gather Town via the link above and interact as in the poster session.
Announcement of best paper awards, social events, and more

End of Day 2